During the following cycle of the machine, the contacts B<sub>1</sub> through B4 and G1 through G4 and A1 through A4 are again contacted by the depending brush contacts 406 and 408 of the indexing arm 400 to drive the machine components, as aforedescribed. However, since it is necessary to deliver and apply a rectangular button to the surface of the highway, during this cycle of operation, as the brush contact 406 is brought into contact with the contact 434, connected with the electromagnet 430 of the circuit 410, the cam wheel 412 is indexed bringing the cam lobe 416 into engagement with the 10 cam follower 418 for depressing the reeds and closing the normally open contacts GS, BS and AS. Continued indexing of the arm 400 again brings the contact 408 into engagement with the brush contact B<sub>s</sub> whereupon a circuit is completed between the bus bar 394, through the circuit 410, to a valve 380 connected with the actuator 308 of the brush 32 so that the rotor 262 is caused to engage the surface of the highway and remove the foreign material therefrom.

The next advancement of the arm 400 causes the contact 20 406 to engage the contact  $G_s$  which serves to connect the bus bar 394 to the actuator 126 of the gate 118 for delivering to the ejector mechanism 150 a rectangular button while at the same time causing the ram 74 to be driven through the chamber 72 of the magazine subsection 36 for delivering another through the gated track to the gate 118 whereat the button is intercepted and retained for subsequent delivery during a subsequent cycle of the machine.

As the machine advances along the surface, the buttons are serially delivered by the button ejector mechanism 150 while 30 the tire 236 serves to engage the upper surface thereof for seating the buttons positively in the globs of delivered adhesive applied by the adhesive applicator 176.

Furthermore, in instances where the machine is being employed to deliver buttons to a surface having gentle curves, the 35 brush is arcuately displaced in a horizontal direction about the pivot point 290 through an operation of the push-pull linkage 366. It is important to note, however, in instance where the curves encountered are rather sharp, or for any other reason, the boom may be disconnected at the clevis 376 and the housing 280 of the brush fixed relative to the bracket 284 by screwthreaded studs 292. The machine then functions as aforedescribed without the booms.

As the machine continues along the surface of the highway, the cycles are repeated in pairs of cycles with four circular buttons being applied during a first cycle, followed by four circular buttons and a rectangular button during the second cycle. Since the operation for each mechanism of the machine has herebefore been provided in conjunction with the description of the mechanism, a detailed description of the operation thereof is omitted at this point in the interest of brevity.

In view of the foregoing, it should be readily apparent that the present invention provides an automated lane-divider button applying machine particularly suited for use in applying lane-divider buttons at selected intervals along lane-divider lines of surfaced highways, and includes a fully automated system for cleaning selected areas, depositing globs of adhesive in the cleaned areas and applying circular and rectangular buttons, in predetermined order, in the applied adhesive.

Although the invention has been herein shown and described in what is conceived to be the most practical and preferred embodiment, it is recognized that departures may be made therefrom within the scope of the invention.

Having described by invention, what I claim as new and 65 desire to secure by Letters Patent is:

- 1. An automated lane-divider button applying machine adapted to apply lane-divider buttons to selectively spaced areas of given surfaces, comprising:
  - A. means adapted operatively to remove foreign matter 70 from spaced areas of a given surface;
  - B. adhesive applicator means for depositing a predetermined quantity of adhesive at each of the selected areas;
  - C. button applicator means for delivering and seating lanedivider buttons within the deposited adhesive; and

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- D. a mobile frame operatively supporting said means for displacement relatively to the spaced areas.
- 2. An automated lane-divider button applying machine, comprising:
- A. a mobile frame;
- B. a prime mover associated with the frame for driving said frame along a selected path of travel and over a surface;
- C. a steering mechanism for controlling directions of travel for said frame;
- D. a button depositing system mounted on said frame including,
  - means defining a surface cleaner for cleaning areas of a button receiving surface;
  - means defining an adhesive applicator for applying globs of adhesive to the cleaned areas; and
  - means defining a button applicator for applying buttons to the applied globs of adhesive; and
- E. machine control and sequencing means including pneumatic actuators adapted to activate the surface cleaner, the adhesive applicator and the button applicator in a preselected sequence, whereby the machine is activated sequentially to clean surface areas for receiving globs of adhesive, to apply globs of adhesive to the areas and to apply buttons to the applied globs of adhesive.
- 3. The machine of claim 2 wherein the machine control and sequencing means includes a plurality of electrically activated pneumatic actuator control valve drive units and an electrical control circuit connected with the units adapted to couple the units with a source of electrical energy for achieving a selected actuation of the actuators for thereby imparting to the machine sequenced operations.
  - 4. The machine of claim 3 wherein the timer includes:
  - A. a driven rotor arm having a plurality of interconnected electrical contact brushes depending therefrom;
  - B. circuit means continuously connecting a source of electrical energy to said brushes;
  - C. a plurality of electrical contacts disposed within the path of the brushes adapted sequentially to be engaged thereby;
  - D. electrical leads electrically connecting said contacts with said motors, whereby the motors are caused to be energized as the contact brushes are caused to engage the contacts; and
- E. drive means adapted to rotate the rotor arm at selected rates or rotation, whereby the hydraulic motors are sequentially and selectively connected with a source of electrical energy as the rotor arm is caused to be rotated by the drive means.
- 5. The machine of claim 4 wherein the rotor drive means includes:
  - A. a wheel disposed in operative engagement with the given surface and adapted to be driven in rotation thereby;
- B. a cam plate operatively coupled with said wheel and adapted to be driven in rotation thereby, and
- C. a cam-driven indexing drive linkage coupled between the rotor arm and the cam plate for indexing the rotor arm at predetermined intervals of wheel rotation.
- 6. An automated lane-divider button applying machine adapted to be driven and sequentially operated for applying lane-divider buttons of the type including a supporting planar surface and an upper light-reflecting surface at predetermined intervals along the surface of a highway for thereby delineating highway traffic lanes, comprising:
  - A. mobilized vehicle, including a steering mechanism and a prime mover adapted to be controlled by an operator for directing the machine along a given path above a selected surface of a given highway;
  - B. a surface cleaner mounted on the vehicle and adapted to remove foreign material from selected areas of the surface:
  - C. an adhesive applicator mounted on the machine adapted to apply globs of adhesive at each of the selected areas from which foreign matter has been removed;